(When Filled In)

R & D CAT	TALOG FORM	26 January 1966	
Automatic Target Recognition Program		s sponsored long range R&D program ated target recognition devices to	
5. class of contractor Industrial R&D: Manufacturer	6. TYPE OF CONTR	RACT	
7. FUNDS	8. REQUISITION NO.	9. BUDGET PROJECT NO.	
FY 19 \$		NP-AT-0	
FY 1966	10. EFFECTIVE CONTRACT D (Begin - end)	A.A Secret	
FY 1967	April 1966 - Janu	T Unclassified w Searet	
12. RESPONSIBLE DIRECTORATE/OFFICE/PRO	JECT OFFICER TELEPHONE EX	XTENSION	
DDI/NPIC/P&DS/			
	tion processes. A p	ssance materials will demand vastly program to develop automated inter-	
14. TYPE OF WORK TO BE DONE			
Applied Research			
15. CATEGORIES OF EFFORT			
MAJOR CATEGORY	Q	SUB-CATEGORIES	
Automatic Target Recognition	Computers Pattern Recognition		
	Optical Filtering		
	Scanni	ing	
and sub-systems of the ultim laboratory research, breadbo	etailed designs and ate ATR system. Th arding, and evaluat	d recommendations for components nese designs will be based on tion of several potential ATR Implications and expected (Contd)	
which will incorporate a num consultant contracts with ot	ecognition Program ber of sub-contract her companies and i	is to be awarded as a prime contrac	
tional page if required)		tomated image recognition systems	
is based upon the following operations: (a) the acquisi will continue to increase; (c) t	predicted trends in tion rate, hence th b) the information here are increasing	reconnaissance and intelligence ne volume, of operational imagery content per unit area of imagery g requirements from intelligence agery, both in variety and degree	
		e more complex with the use of (Cont	
19. APPROVED BY AND DATE			
OFFICE DEPUTY DIR	RECTOR	DDCI	
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- 16. results of the long range program (5 years) are outlined in paragraph 18, below.
- 17. that all other significant ATR work in the country will be scrutinized and evaluated for potential usefulness to this program and to avoid duplicative effort.
- 18. color, infrared, radar, etc; (e) the allowable time to extract certain types of information from imagery will decrease; (f) it is a long and uncertain process to recruit, train, and retain the very large number of interpreters which would be required to fully satisfy these future conditions by entirely 'manual' techniques. It is therefore incumbent upon the Government to develop automated image recognition systems to aid the fully qualified interpreter in performing some of his less complicated tasks. This, in turn, will allow the interpreter to concentrate on the more complex interpretative problems.

The types of exploitation tasks which are now considered to be amenable to automation include the following: (a) screening of large volumes of imagery to separate 'sterile' portions of the film from those containing possible targets of interest to the interpreter; (b) classification of targets into broad type-categories; (c) re-scanning of large volumes of previous coverage to search for one-type of target of known configuration; (d) change detection on multiple coverage of targets; (e) automatic recognition and correlation of map area to image area in scanning operations; (f) automatic inventory of similar objects within an image field.

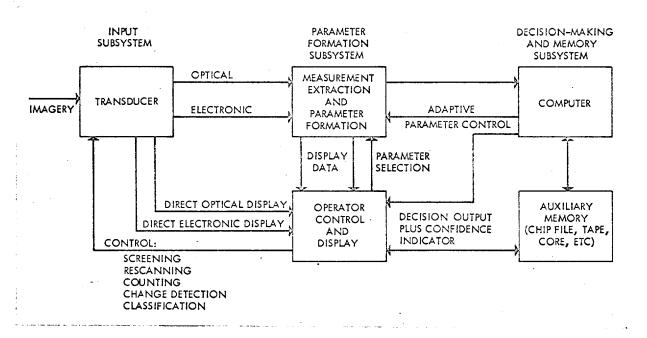
The feasibility of machine recognition of targets on aerial photography has been demonstrated. It has been demonstrated by various electro/optical/digital techniques, several of which have been hardware implemented in crude prototype systems. Some of the more promising ATR developmental systems are; the Tactical Target Recognizer for the Army; the Natural Image Computer for GIMRADA; the Automatic Target Recognition Device for RADC; and the Minos II by Stanford for Ft. Monmouth. All of the systems developed to date satisfy some of the required objectives, but all have serious deficiencies when related to the ultimate operational requirements. These are: (a) excessive processing time per unit area of film (the bandwidth limit); (b) the resolution and dynamic ranges are too low; (c) versatility not adequate for the many variables of target images; (d) recognition accuracies need to be improved. These deficiencies are considered to be the major problems to be solved in the proposed ATR program. There now appears to be considerable promise that the development of ATR systems can be realized which will overcome most of these deficiencies.

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18. The configuration of the ultimate ATR system, or even the subsystems, is unknown at this point. The purpose of the initial contracted effort will be investigation of several sub-system techniques, laboratory breadboarding of the most promising sub-systems and thorough evaluation of their potential. As a result of this initial effort, a fairly firm system configuration can then be designed. Our knowledge at this date indicates that there probably will be four functional sub-systems: an input sub-system; an image feature extraction sub-system; a decision-making and memory sub-system (computer); and an interpretation display and control console. A conceptual diagram of an ATR system is shown below.



CONCEPTUAL BLOCK DIAGRAM OF AN AUTOMATIC TARGET RECOGNITION SYSTEM

Of the fifteen proposals received for this program	<i>'</i> 1		
proposal was clearly the most prom			
cally, and proposed the most definitive program plan, or	rganization,		
and management.	would		
be the prime contractor with	as the leading		
sub-contractor. Other proposed sub-contractors are:			
These companies represent a good national			
cross-section of ATR talent and experience. The first phase of			
this program would be a concentrated and concerted nine-month			
effort by all the companies concerned and would encompanies reached and would encompanies.	ss the following		

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- 18. (a) Problem definition to determine, more specifically, the priority of tasks toward which an ATR system should be initially designed; and to define NPIC requirements for processing time, accuracy, resolution, types of targets, etc.
 - (b) Evaluation of existing techniques for their potential application to NPIC requirements of the ultimate system (as determined above)
 - (c) Study and evaluation of human factors which might be involved in an ATR system. These include: man-machine interface factors; types of display and control; and P.I. confidence factors with relation to machine decisions
 - (d) Preliminary sub-system design and breadboard testing of potential sub-systems
 - (e) Sub-system and system specifications
 - (f) Formulation of a detailed long range development program.

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